

Coefficients of ergodicity for imprecise Markov chains

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ISIPTA'09, Durham, 14 – 18 July 2009

Outline

- 1 Imprecise Markov chains
 - Introduction
 - Representation of imprecise Markov chains
- 2 Coefficients of ergodicity for imprecise Markov chains
 - Coefficients of ergodicity
 - Coefficients of ergodicity for imprecise Markov chains
 - Generalisations of distance functions to imprecise probabilities
 - Uniform coefficient of ergodicity
 - Weak coefficient of ergodicity
- 3 Conclusion

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Markov chains

- A (discrete time) **Markov chain** is a random process with the **Markov property**...
- ...which means that future **states** only depend on the present state and not on the past states.
- This dependence is expressed through **transition probabilities**:

$$\begin{aligned} P(X_{n+1} = j | X_n = i, X_{n-1} = i_{n-1}, \dots, X_0 = i_0) \\ = P(X_{n+1} = j | X_n = i) = p_{ij}^n \end{aligned}$$

for every $n \in \mathbb{N}$.

- The knowledge about the first state is given by **initial probability**

$$P(X_0 = j) = q_j.$$

Imprecise Markov chain

- A Markov chain has many parameters which may not be known precisely.
- An **imprecise Markov chain** is a Markov chain where the imprecise knowledge of parameters is built into the model...
- ...and reflected in the results:
 - probabilities of states at future steps;
 - long term distributions.

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Representation with sets of probabilities

- The uncertainty of parameters can be expressed through **sets of probabilities**:
 - instead of single precisely known initial and transition probabilities we take sets of possible candidates.
- Let \mathcal{M}_n be the set of possible distributions at step n and \mathcal{P} the set of possible transition matrices.
- The following relation must hold:

$$\mathcal{M}_{n+1} = \mathcal{M}_n \cdot \mathcal{P}.$$

- Another important question is whether the sets converge to some limit set \mathcal{M}_∞ and what can we say about this convergence.

Representation with expectation operators

- The sets \mathcal{M}_n are usually assumed to be convex.
- Convex sets of probabilities can equivalently be expressed through (lower) **expectation operators**

$$\underline{P}_n[f] = \min_{p \in \mathcal{M}_n} E_p[f],$$

where f is a real valued map on the set of states.

- Sets of transition matrices can be represented through (lower) **transition operators**:

$$\underline{T}[f] = \begin{pmatrix} \underline{T}_1[f] \\ \vdots \\ \underline{T}_m[f] \end{pmatrix}.$$

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Coefficients of ergodicity

- **Coefficients of ergodicity** or **contraction coefficients** measure the rate of convergence of Markov chains.
- They can be expressed in terms of distances between sets of transition matrices.
- Let p be a stochastic matrix without zero columns.
- The value $\tau(p)$ of a coefficient of ergodicity satisfies:
 - $0 \leq \tau(p) \leq 1$;
 - $\tau(p_1 p_2) \leq \tau(p_1) \tau(p_2)$;
 - $\tau(p) = 0$ iff p has rank 1: $p = \mathbf{1}v$ for some vector v .
- Clearly: $\tau(p) < 1$ implies that powers p^n converge to a matrix with rank 1, which is equivalent to unique convergence of the corresponding Markov chain.

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Calculation and generalisation

- A coefficient of ergodicity can be calculated as

$$\tau(p) = \max_{i,j} d(p_i, p_j),$$

where p_i and p_j are the i -th and the j -th row of p ; and

$$d(p_i, p_j) = \max_{A \subseteq \Omega} |p_i(A) - p_j(A)|.$$

- We can generalise this to imprecise Markov chains if the distance function d is generalised to imprecise probabilities.
- This can be done in different ways with different implications to imprecise Markov chains.

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Hausdorff metric

- The **Hausdorff metric** makes the set of compact non-empty subsets of a metric space a metric space.
- It is defined by:

$$d_H(X, Y) = \max \left\{ \sup_{x \in X} \inf_{y \in Y} d(x, y), \sup_{y \in Y} \inf_{x \in X} d(x, y) \right\}.$$

- It can be used to measure distances between closed sets of probability distributions on finite measurable sets.
- The Hausdorff distance is equal to 0 iff the sets are equal.

Distances between expectation operators

- Using lower expectation operators there is another way to measure the distance between imprecise probabilities:

$$d(\underline{P}, \underline{P}') = \max_{0 \leq f \leq 1} |\underline{P}(f) - \underline{P}'(f)|.$$

- Our first result:

Let \mathcal{M}_1 and \mathcal{M}_2 be closed convex sets of probabilities and let \underline{P}_1 and \underline{P}_2 be their lower expectation operators. Then:

$$d(\underline{P}_1, \underline{P}_2) = d_H(\mathcal{M}_1, \mathcal{M}_2).$$

Maximal distance between imprecise probabilities

- Sometimes we need the maximal distance between sets of probabilities:

$$\max_{\substack{p_1 \in \mathcal{M}_1 \\ p_2 \in \mathcal{M}_2}} d(p_1, p_2)$$

- We show that this is equal to

$$\max_{A \subset \Omega} \max\{\bar{P}_1(1_A) - \underline{P}_2(1_A), \bar{P}_2(1_A) - \underline{P}_1(1_A)\}.$$

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Uniform coefficient of ergodicity

- Let \mathcal{P} be a set of transition matrices.
- Let \mathcal{P}_i denote it's i -th row.
- The **uniform coefficient of ergodicity** is defined as

$$\tau(\mathcal{P}) = \sup_{p \in \mathcal{P}} \tau(p)$$

by Hartfiel (1998).

- Using a previous result we can see that

$$\tau(\mathcal{P}) = \max_{1 \leq i, j \leq m} \max_{A \subset \Omega} \overline{T}_i(1_A) - \underline{T}_j(1_A),$$

where \underline{T}_i and \overline{T}_j are lower and upper expectation operators corresponding to \mathcal{P}_i and \mathcal{P}_j respectively.

Convergence

- A set \mathcal{P} of transition matrices such that $\tau(\mathcal{P}^r) < 1$, for some $r > 0$, is called **product scrambling**.
- The following convergence result holds (Hartfiel (1998)):

Let \mathcal{P} be product scrambling. Then

$$d_H(\mathcal{M}_0 \mathcal{P}^n, \mathcal{M}_\infty) \leq K \beta^n$$

for some constants K and β ; and \mathcal{M}_∞ is a unique compact set of probabilities, independent from \mathcal{M}_0 .

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Weak coefficient of ergodicity

- The previous requirements are clearly sufficient for convergence, but too strong (this follows from the results of de Cooman, Hermans, Quaeghebeur (2009)).
- We need another coefficient of ergodicity to describe this type of convergence.
- Instead of taking maximal possible distances between rows of imprecise transition matrices, we take a distance that reflects only the difference between the rows.
- Hausdorff distance seems a good candidate.

Definition of the weak coefficient of ergodicity

- We define the **weak coefficient of ergodicity** by means of lower expectation operators.
- Let \underline{T} be a lower transition operator with rows \underline{T}_i .
- Then we define the weak coefficient of ergodicity as

$$\rho(\underline{T}) = \max_{i,j} d(\underline{T}_i, \underline{T}_j),$$

which is equal to the Hausdorff distances between the corresponding sets.

Convergence

- A lower transition operator \underline{T} such that $\rho(T^r) < 1$, for some $r > 0$, is called **weakly product scrambling**.
- For an imprecise Markov chain with weakly product scrambling lower transition operator we have the following result:

Let \underline{T} be weakly product scrambling. Then

$$d(\underline{P}_0 \underline{T}^h, \underline{P}_\infty) \leq K \beta^h$$

for some constants K and β ; and \underline{P}_∞ is a unique lower expectation operator, independent from \underline{P}_0 .

Conclusions

- The main new results of our paper are:
 - equivalence between the Hausdorff distance between sets of probabilities and the distance between the corresponding lower expectation operators;
 - the definition of a new coefficient of ergodicity for imprecise Markov chains and the equivalent definitions of the existing coefficients.
- Possible directions of future work include:
 - generalisations of other types of coefficients of ergodicity to the imprecise case;
 - comparison between our results and other similar results in this field.